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Collaborative autonomous vehicles as a new mode of transportation Prof. dr. ir. B. Jayawardhana



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Contents

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- > Autonomy in transportation systems
- > Short overview of *distributed* formation control
- > **Cooperative** autonomous vehicles as a new mode of transportation
- > Challenges and outlook

Autonomy in transportation systems



Coming soon:

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- > Autonomous ship (TRL high)
- Autonomous jet airliner (TRL medium)
 Proof-of-concept: Northrop Grumman X-47B
- > Cooperative autonomous vehicles (TRL low-medium)

Cooperative autonomous systems

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Cooperative autonomous systems

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Credit: Rush Hour movie by Fernando Livschitz

Formation control (in short)

- > Coordination of multiple agents to accomplish an objective
- > Advantages

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- Reduce system costs
- Scalability
- Structure flexibility
- Increase of robustness and efficiency
- > Typical characteristics
 - Onboard (local) sensing equipment
 - Onboard (local) computation ability
 - No global information
- > Important issue = stability





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Group motion

- Leader-follower approach
 has many drawbacks
- Behaviour approach

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- requires continuous central coordination and global information
- Virtual structure
 - suitable for cooperative autonomous vehicles



Formation control of mobile robots

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Formation control for industrial robots

Discrete Technology & Production Automation University of Groningen



Formation control of drones



Challenges

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- > Controlling group behavior via local action
- > Cooperative area mapping, localization and coverage
- > Guaranteeing safety and robustness of group behavior
- > Dynamic interaction with the environment
- > Cooperation among different autonomous vehicles
 - Including different drones and between aerial and ground vehicles



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- > Autonomy has been present in modern transportation systems
- Cooperative autonomous vehicles can be a new mode of transportation system



Thank you

























































